

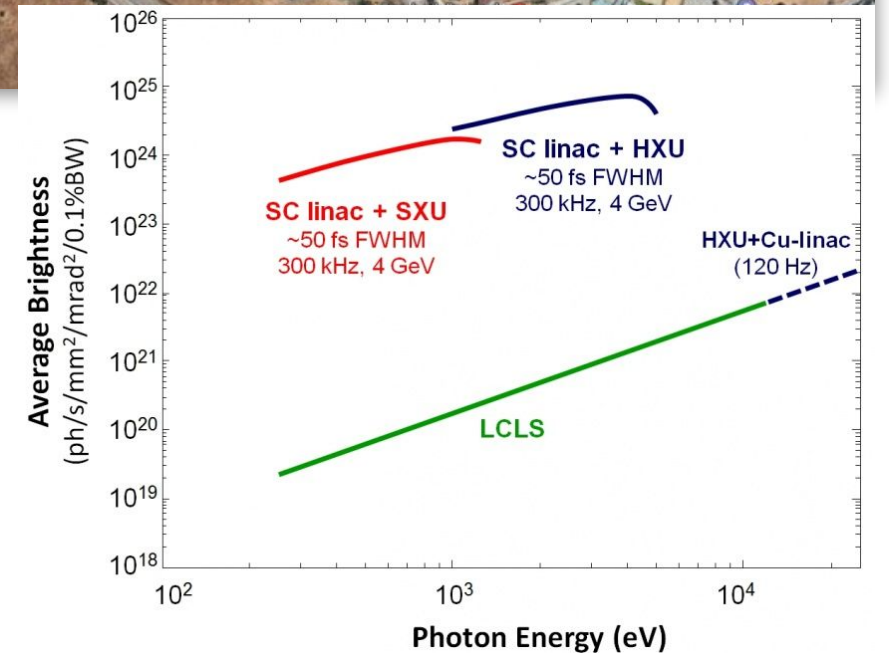
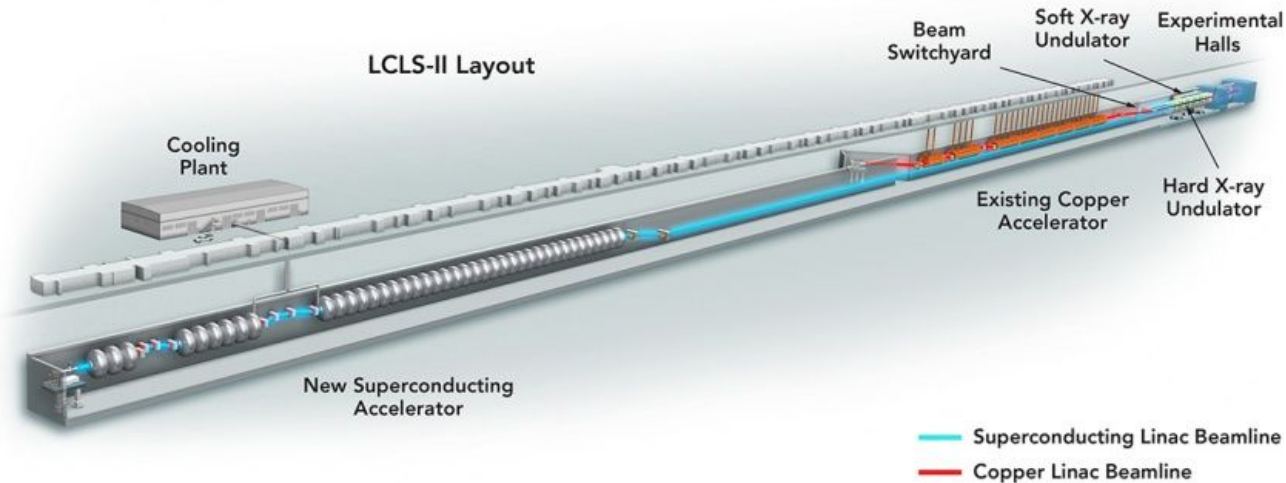
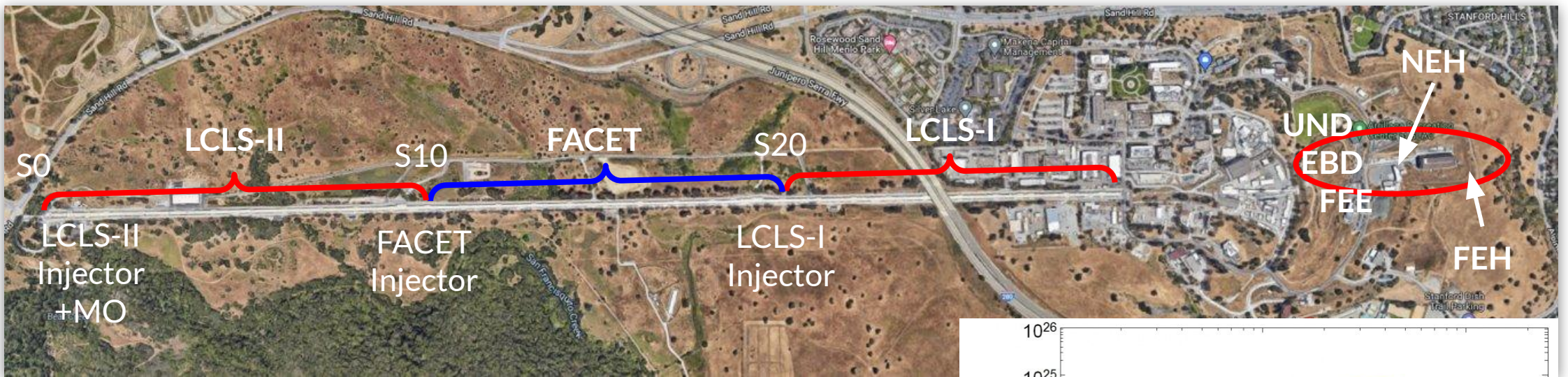
The LCLS-II Experiment Control System



TH2BC003

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LCLS-II Overview



LCLS-II TTO KPP Progress, Sept 23, 2023

(TTO KPP = Transition To Operations, Key Performance Parameters)

Performance Measure	Threshold (5 kW beam)	Objective (120 kW beam)	Measurements
Variable gap undulators	2 (soft and hard x-ray)	2 (soft and hard x-ray)	
Superconducting linac-based FEL system			
Superconducting linac electron beam energy	3.5 GeV <input checked="" type="checkbox"/>	≥ 4 GeV	Spectrometer bend (magnet strength, screen)
Electron bunch repetition rate	93 kHz <input checked="" type="checkbox"/>	929 kHz	BPM's, laser rate
Superconducting linac charge per bunch	0.02 nC <input checked="" type="checkbox"/>	0.1 nC <input checked="" type="checkbox"/>	Toroid, Faraday cup
Photon beam energy range	250–3,800 eV <input checked="" type="checkbox"/>	200–5,000 eV	Absorption edges, spectrometer
High repetition rate capable end stations	≥ 1 <input checked="" type="checkbox"/>	≥ 2 <input checked="" type="checkbox"/>	N/A
FEL photon quantity (10^{-3} BW) per bunch	5×10^8 (10x spontaneous) @2,500 eV <input checked="" type="checkbox"/>	$> 10^{11}$ @ 3,800 eV	Gas energy monitor, GMD, Spectrometer
Normal conducting linac-based system			
Normal conducting linac electron beam energy	13.6 GeV <input checked="" type="checkbox"/>	15 GeV <input checked="" type="checkbox"/>	Spectrometer bend (magnet strength, screen)
Electron bunch repetition rate	120 Hz <input checked="" type="checkbox"/>	120 Hz <input checked="" type="checkbox"/>	BPM's, laser rate
Normal conducting linac charge per bunch	0.1 nC <input checked="" type="checkbox"/>	0.25 nC <input checked="" type="checkbox"/>	Toroid, Faraday cup
Photon beam energy range	1–15 keV <input checked="" type="checkbox"/>	1–25k eV <input checked="" type="checkbox"/>	Absorption edges, spectrometer
Low repetition rate capable end stations	≥ 2 <input checked="" type="checkbox"/>	≥ 3 <input checked="" type="checkbox"/>	N/A
FEL photon quantity (10^{-3} BW ^a) per bunch	10^{10} (lasing @ 15 keV) <input checked="" type="checkbox"/>	$> 10^{12}$ @ 15 keV	Gas energy monitor, GMD, Spectrometer

ECS Team



Delivery 19 (+3s +1m)

- HW & SW Deployment
- User and Experiment Support
- Data Analysis
- Instrumentation Expertise

- 3 complimentary teams
- ~3 dozen personnel
 - Staff / Students
 - Matrixed Staff
 - Contractors

Platform Dev 12 (+2m)

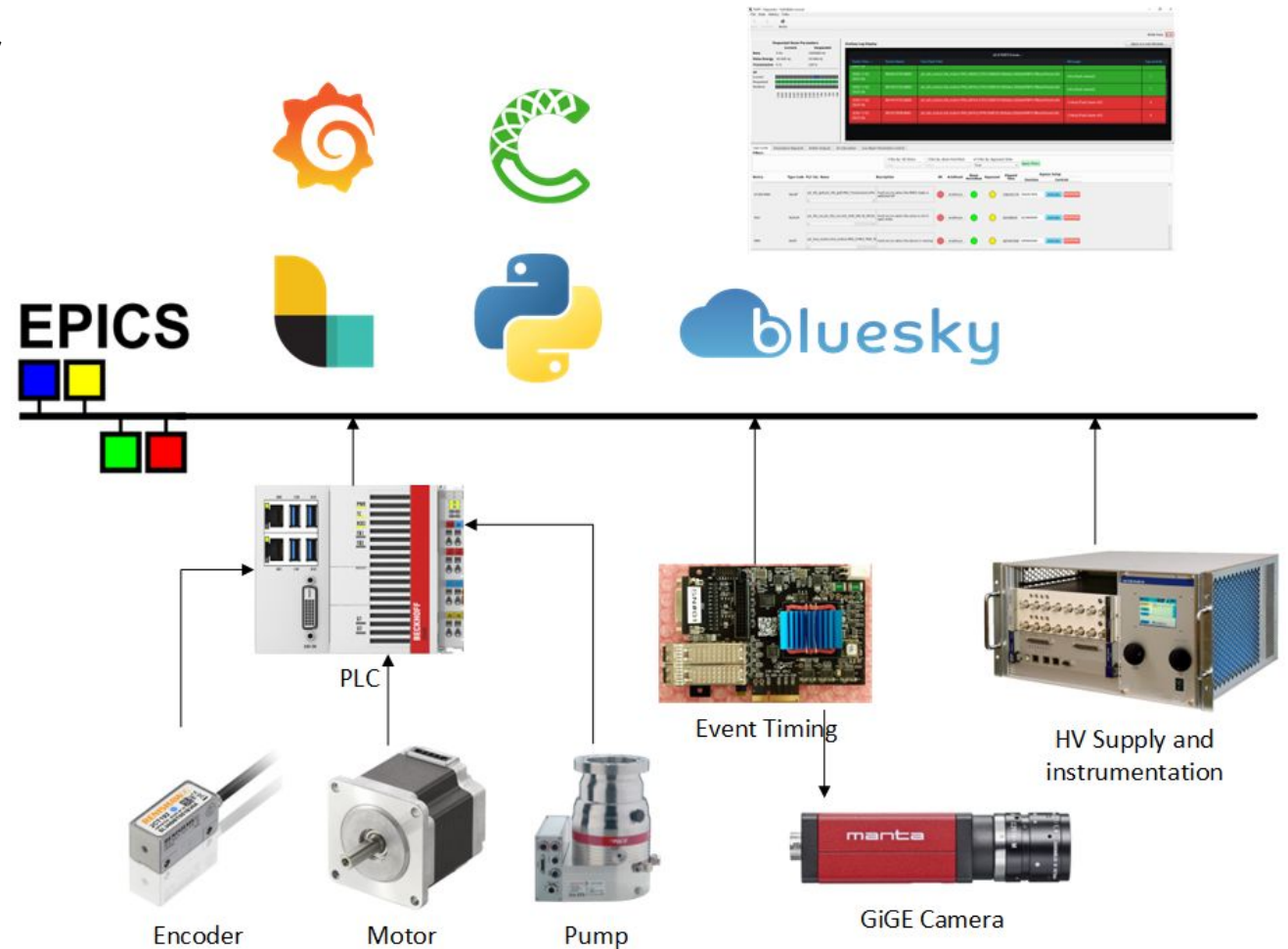
- Core Hardware and Software Development
- Expert Support
- Project Management

IT Systems (1m)

- Core IT Development
- Deployment
- Expert Support

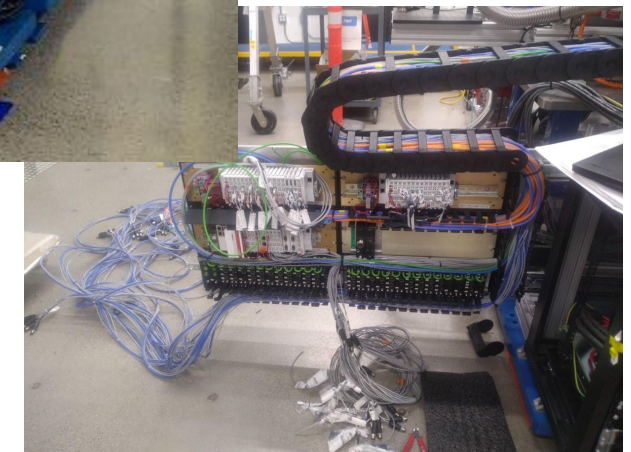
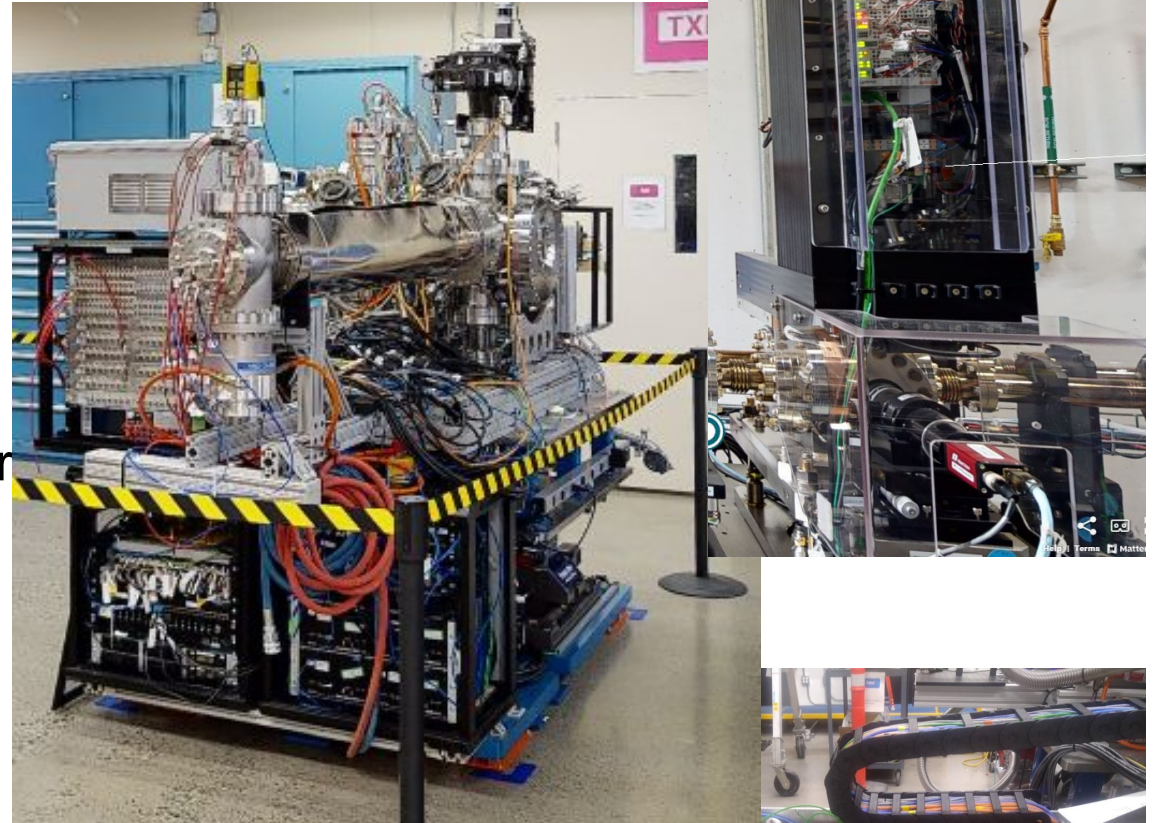
LCLS-II ECS Overview

- The controls core system has been redesigned for the LCLS-II beam under XTES and L2S-I projects. Performance verified:
 - EBD, FEE
 - TMO
 - RIX.
- Controls system and subsystems
 - Preemptive Machine Protection
 - Motion
 - Vacuum
 - Lasers
 - Sensors
 - EPICS
 - Logging and Alerts
 - User Interfaces

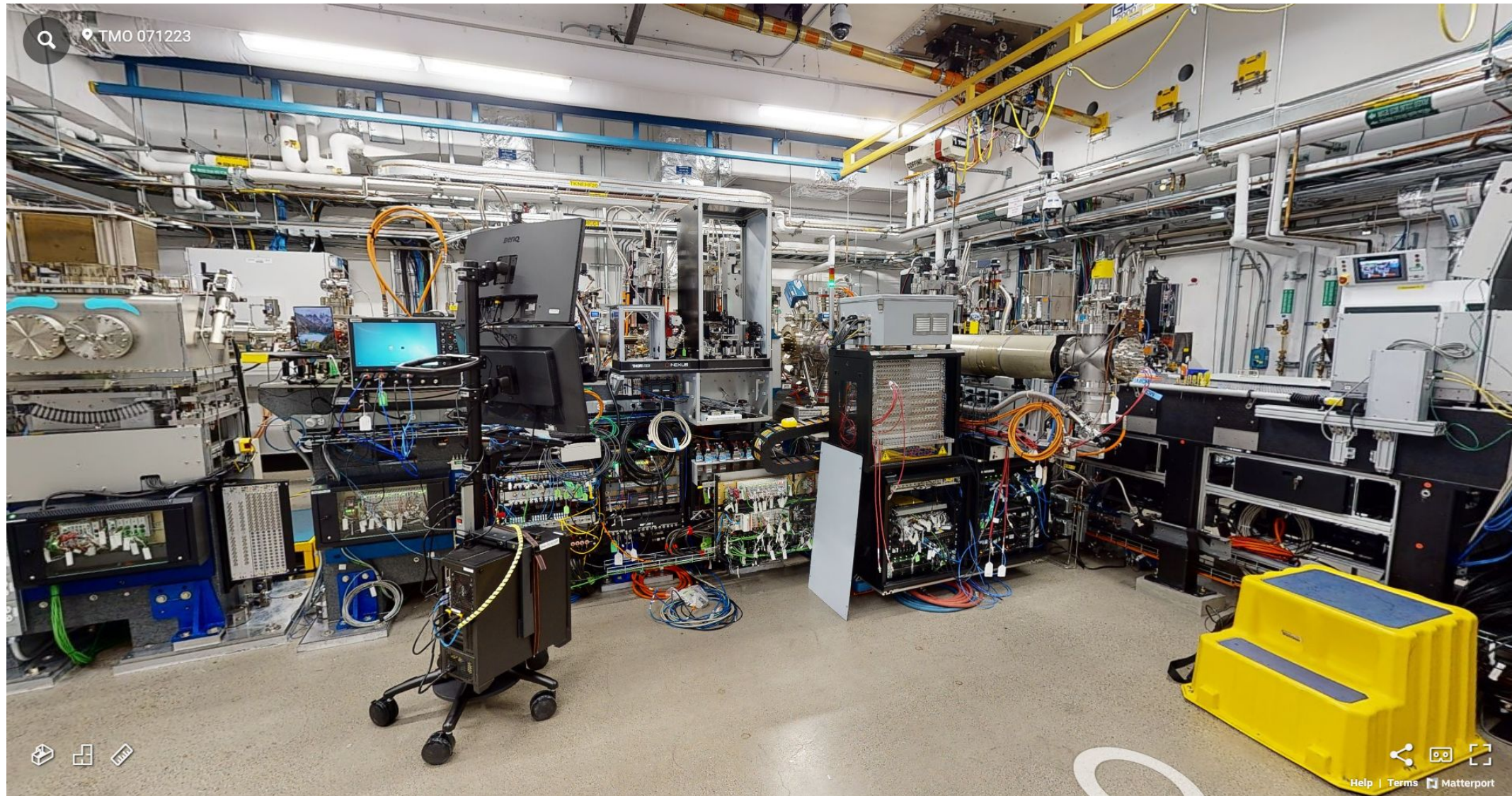


LCLS-II ECS Platform - Hardware

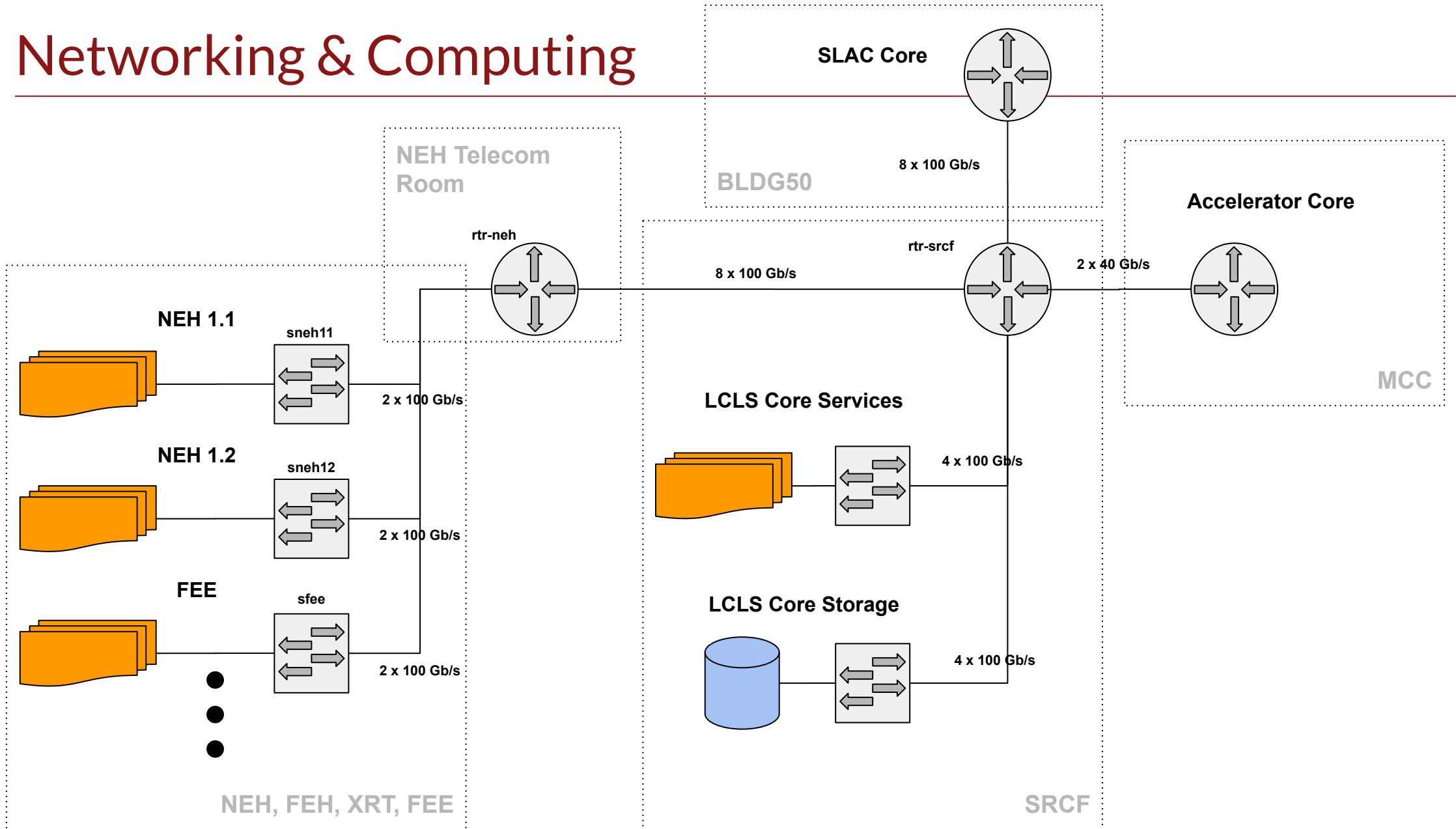
- Controls are mounted on DIN rails on the device.
 - Motion terminals
 - IO Terminals
 - Power distribution
 - 24V, 48V from DCT
 - DIN rail DC-DC converters modules for other voltage requirements.
- Control interface connection
 - Power (24V, 48V)
 - EtherCAT
- EtherCAT distribution junction
 - Connects all components to Motion PLC
 - Star topology
- Fully integrated into PMPS.



LCLS-II ECS - Example Installation - TMO

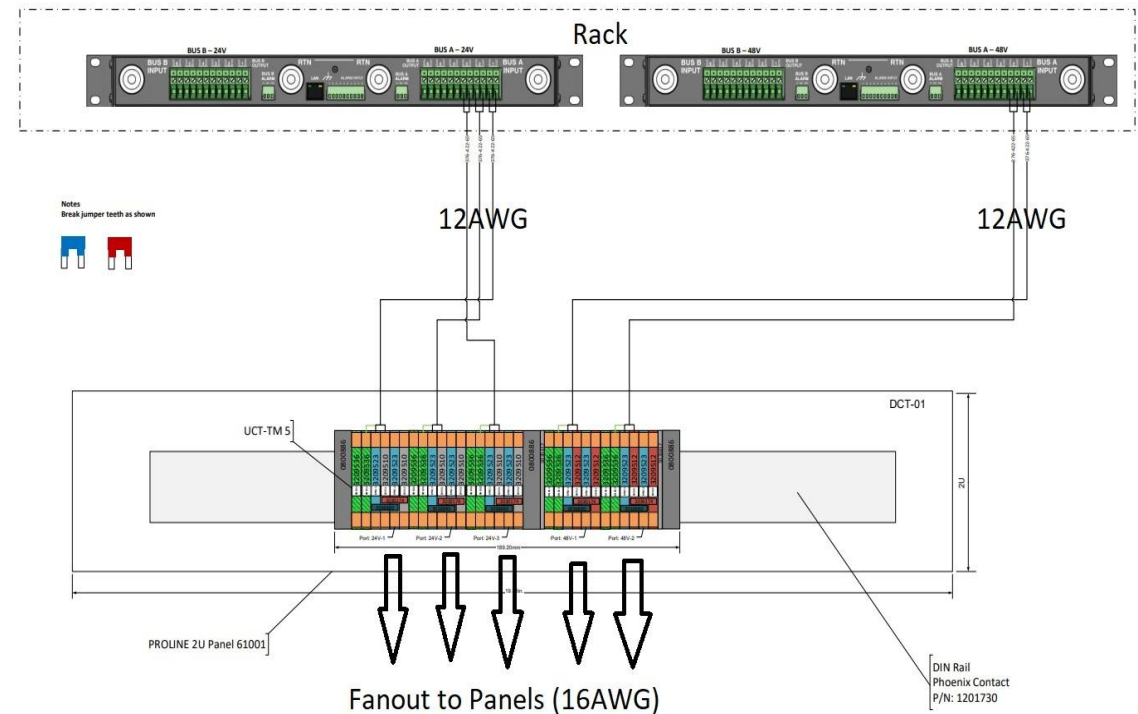


Networking & Computing



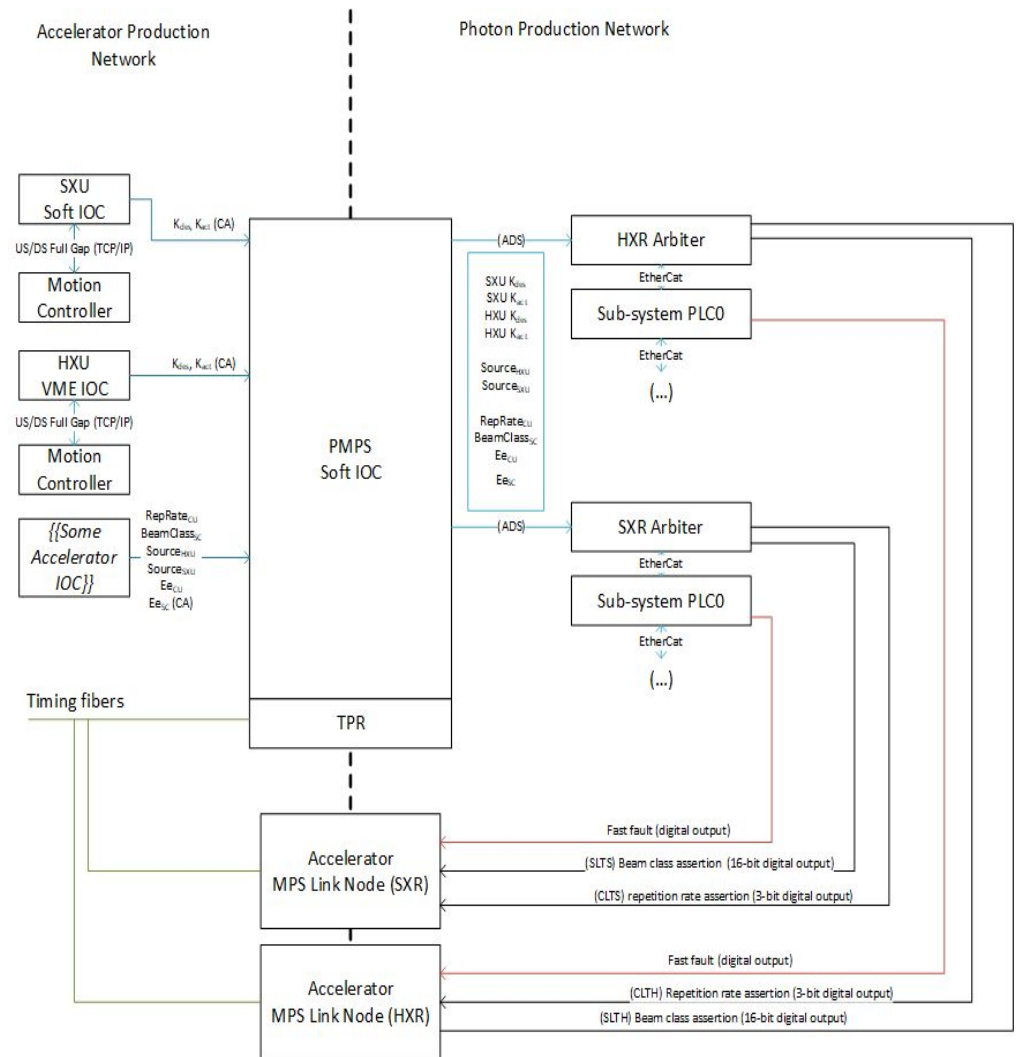
Low-voltage DC Power System

- Provides a distributed low voltage power delivery system for controls
- Using high current AC-DC rectifiers to convert to 24VDC or 48VDC, easy to swap.
- Distribute 24VDC and 48VDC using ICT distribution unit
- 15A DC channels are individually controlled and monitored remotely



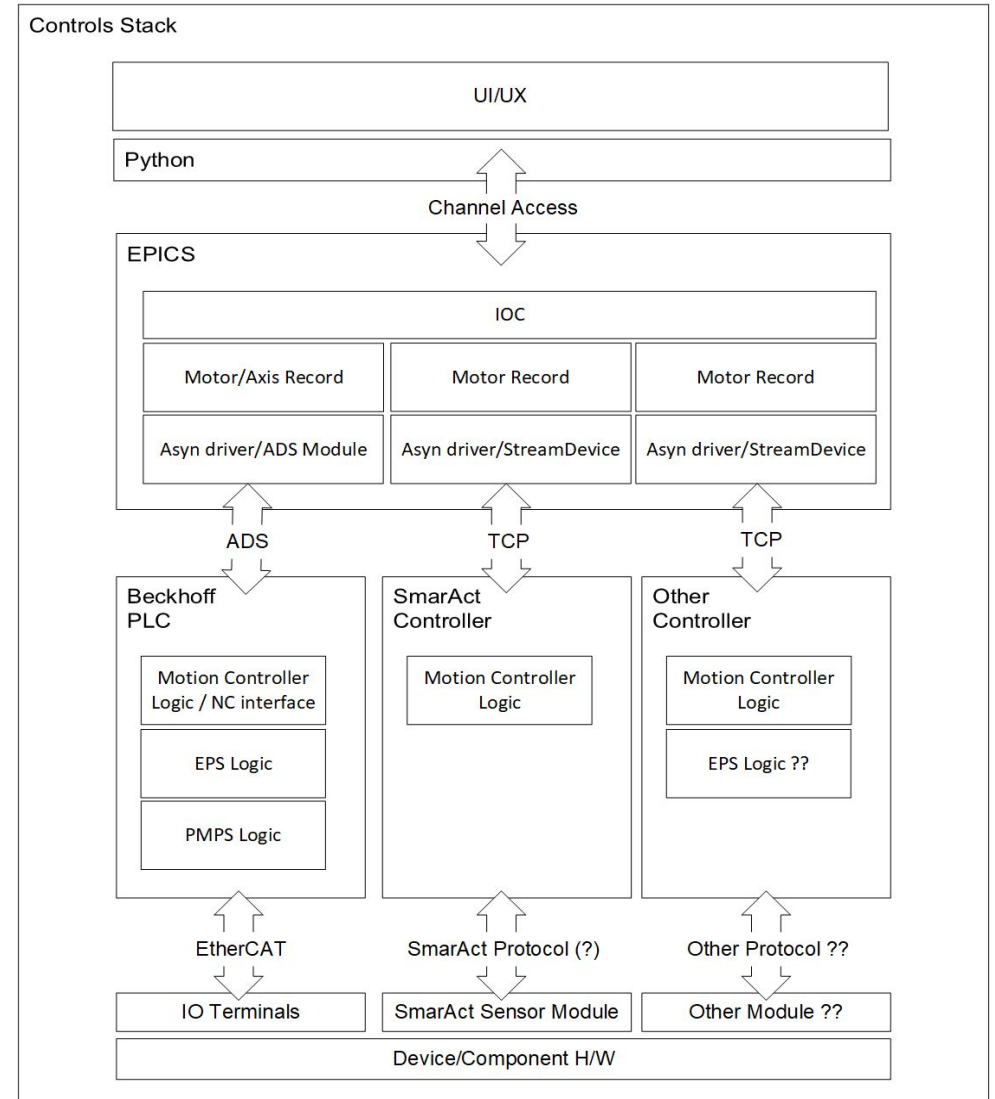
Pre-emptive Machine Protection System

- PMPS utilizes PLC controllers integrating various actuators, vacuum transducers, absolute encoders, dry-contact switches, flowmeters, and temperature sensors to control and monitor device states and beam parameters through the EtherCAT bus.
- Preemptive and reactive elements are kept separate.
- PLC code framework for implementing new devices, interlocks and transition manager.
- Dedicated EPICS IOC for relaying undulator K, electron energy, and active beamclass to the PMPS



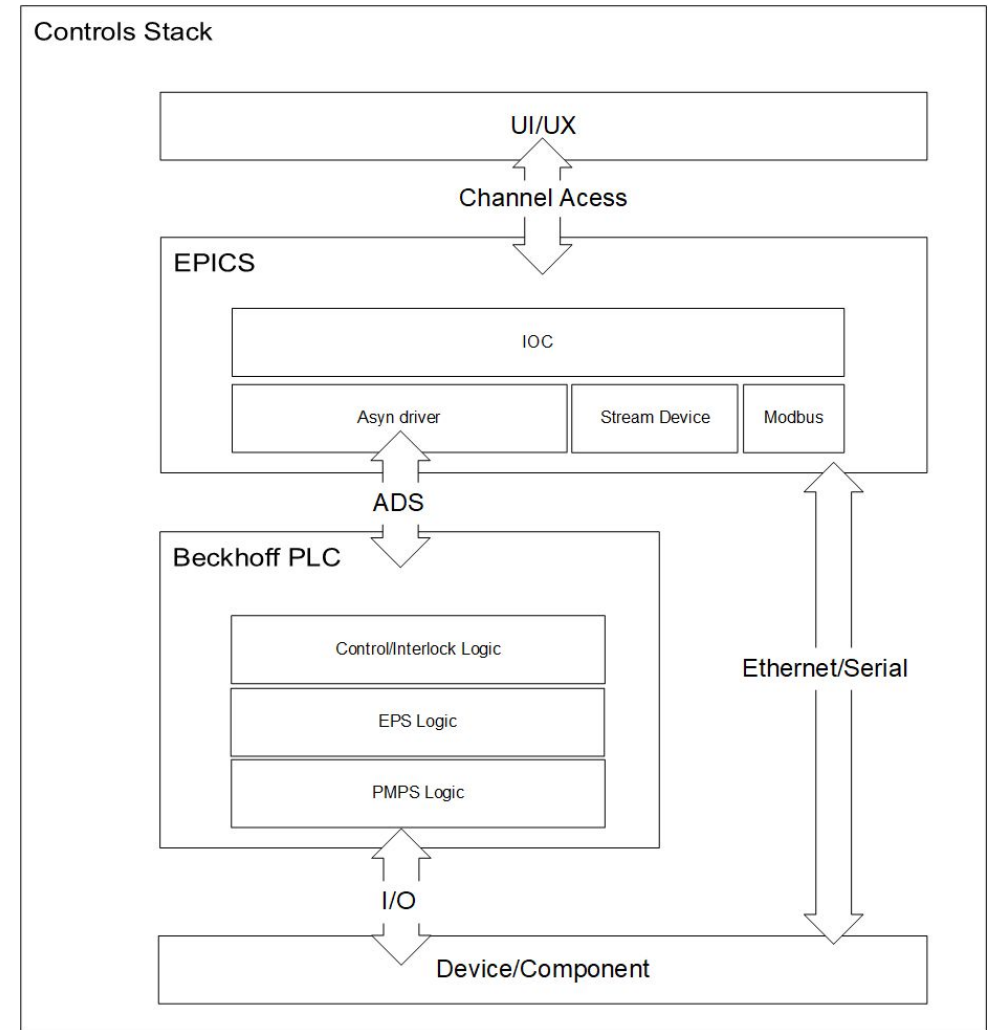
Motion System

- Axis coordination and basic automation
- EPS - Equipment Protection System
 - Prevent crashes, collisions, damage
- PMPS Interface
 - Provide timely readbacks to PMPS via Beckhoff EtherCAT interface
- State Mover
 - Prevent unsafe states preemptively
- BPTM
 - Ensures safe beam condition before transitions.
- MPS reactive fault via digital output



Vacuum System

- Integration of all vacuum devices all the way to EPICS and PyDM.
- Vacuum supported devices
 - Gauges: hot cathodes, cold cathodes, pirani, combo gauges, rad hard gauges.
 - Pumps: Ion pumps (gamma and nextorr), Turbo pumps (Pfeiffer, Leybold, Ebara, Agilent), Roughing pumps.
 - Valves: Various pneumatic valves, Pfeiffer EVR116, MKS 248 variable valve, Motorized valves.



Thank You

Thank You!

- ECS and LCLS teams
- SLAC (esp. AD/TID/LCLS2), and the DOE Office of Science
- Collaborators, especially at NSLSII and the ESS
- Many people in this room or their colleagues who have participated in our many reviews and given invaluable insight and encouragement

See for more detailed content:

WE1BCO04, WE1BCO07, MO4BCO06, TUPDP129