A Digital Twin for Neutron Instruments

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Objectives

Enrich the offer of user tools with the possibility to run a virtual experiment with an ILL instrument.

Training:

- newcomers to the instrument control system
- ▶ users new to a particular instrument, its configuration and capabilities
- Settings optimization: study and optimize instrument settings for a specific configuration to maximize some figure of merit (e.g. intensity vs resolution)
- **Analysis:** improve analysis with better understanding of some background sources and uncertainties (e.g. effect of a possible mis-alignment)
- **Support material:** enrich prosals for demanding beam time with results from simulated data with the specific instrument taking into account its capabilities



Design Requirements

- ▶ usable by users with **no knowledge** in neutron physics
- ▶ use the **familiar interface** of instrument control to configure and start acquisition
- \blacktriangleright simulated data must be treated as the real data \rightarrow written to disk in same format
- ▶ use **state-of-the-art** simulation software (McStas)
- ▶ provide instrument description for public use (McStas experts not using the Digital Twin)
 - possible feedback from power users

Instrument Control Gui

File View Hardware Settings Command Editor Spy User Zoom Help Internal use 4 Hardware Execution D11 settings Go to Edition Instruments > Acquisition Collimation > Axis Wanted position 8.0 v m Actual position 0.0 m 🖉 🖬 Beam parameters Attenuator Measurement type Scattering BeamStop Colimations Attenuator Disphragm N6Wavelength ReartorProver Dianhranms Selector no1: 3(15 x 15) v no2: 7(28 5 x 31) v no3: 7(38 x 55) v no4: 2(50 x 55) > no.5: 2 (50 x 55) Setting N Wavelength 0.5 m 1.5 m 5.5 m 10.5 m 20.5 m Wavelength Detector CheckSPR Wanted 6.00 Å Actual 0.0 Å Wanted 2.00 m Actual 0.00 m Sample environment > RT Tools Bx 253.00 mm Actual 0.00 0 Wanted heamston number Beamston 1 v Current heamston number 1 0.00 mm Actual 0.00 mm O Bange 0.03010 Å-1 0 max down 0.46058 Å-1 0 max up 0.38717 Å-> Alarms End of Launch Pad LaunchPad State: idle

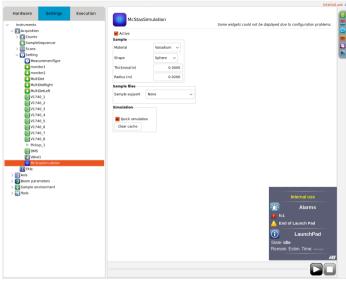
- NOMAD is ILL's Instrument Control System
- ▶ NOMAD core is a c++ server
- The GUI is a java client connecting to the server
- ▶ from the GUI users can:
 - change the instrument settings
 - program the acquisition workflow



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Specific module for simulation settings

File View Hardware Settings Command Editor Spy User Zoom Help



Sample settings

- ▶ shape and size
- material or information about scattering probability from theoretical calculations
- Sample holder from list of pre-configured or custom
 - ▶ shape and size
 - material

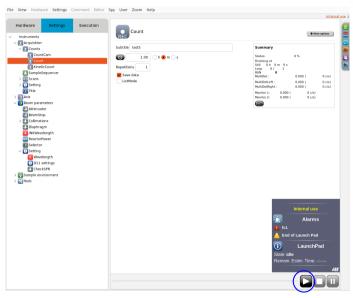
${\bf Sample \ environment} \ from \ list$

of those available for the instrument



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Virtual acquisition



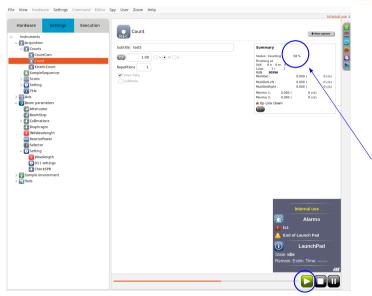
• User can then start a simulation as used to do with the experiment.



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Virtual acquisition



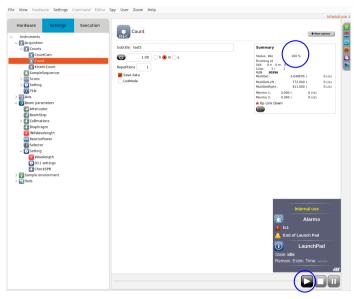
- User can then start a simulation as used to do with the experiment.
- ▶ Feedback on progress



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Virtual acquisition

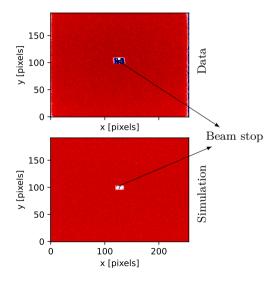


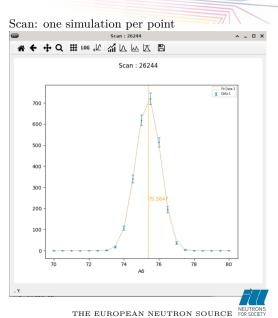
- User can then start a simulation as used to do with the experiment.
- Feedback on progress
- Results available at completion



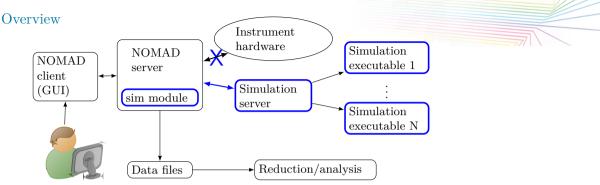
Simulation result

Scattering on empty sample holder





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Software divided into:

1. C++ client API

(used by the NOMAD server's sim module)

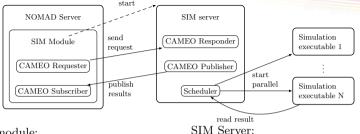
- 2. SIM server
- 3. instrument simulation executables

CAMEO middleware provides:

- APP management (start/stop) also on remote machines
- Communication between managed APPs with high level
 Requester-Responder/Publisher-Subscriber patterns implementation using ZMQ



Communications and interactions



NOMAD's client module:

- 1. Starts the SIM server
- 2. Collects settings and create a request using the SIM client API
 - API guarantees format of request message
- 3. Send the request message (JSON format)
- 4. Waits for simulation result (or error)
- 5. Retrieve the simulation status and result

- process incoming simulation requests
- ▶ assign UID to the request (messages's hash)
- prepare the scheduler with simulation settings
- ► the scheduler starts multiple instances of the simulation executables in parallel
- ▶ retrieve and merge from disk the results
- publish the simulation results



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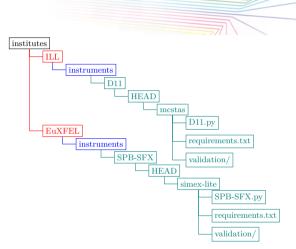
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Simulation executable

- ▶ use state-of-the-art neutron ray-tracing software: Mcstas (ANSI C)
- Instrument description
 - in python using McStasScript and libpyvinyl libraries
 - retrieved from "instrument description repository" (github)
- Instrument executables compiled and binary packages created and installed on execution machines.



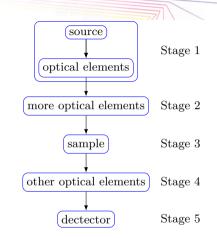


Simulation staging and smart scheduler

Difficult to compete with ILL's high flux: simulation time much larger than acquiring real neutrons for high scattering scamples.

Mitigations:

- optimize instrument description in simulation
- ▶ CPU parallelization vs GPU
- ▶ divide the simulation in stages (different executables)
- map instrument settings to different stages
- re-use previously simulated stages, re-running those with changed parameters





Summary

Objectives achieved:

- ▶ A prototype setup for a digital twin (DT) at ILL has been developed
- ▶ The DT can be used by users with no knowledge about simulation
- ▶ Data are available in the usual format, ready for reduction and analysis via the normal workflow.
- ▶ The client-server model allows further development of different interfaces to the simulation server (e.g. Jupyter notebooks via python API, or other client program)

Further steps:

- ▶ develop a detector description validation scheme
 - \rightarrow tests comparing real data and simulation for some well understood samples
- ▶ reduce simulation time: tune and optimize parallelization





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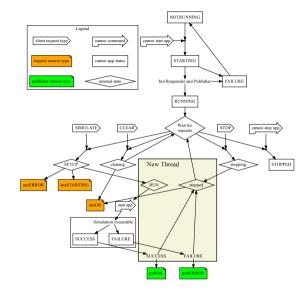
Additional material



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Simulation server diagram





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