

Technical Design Concept and First Steps in the Development of the New Accelerator Control System for PETRAIV

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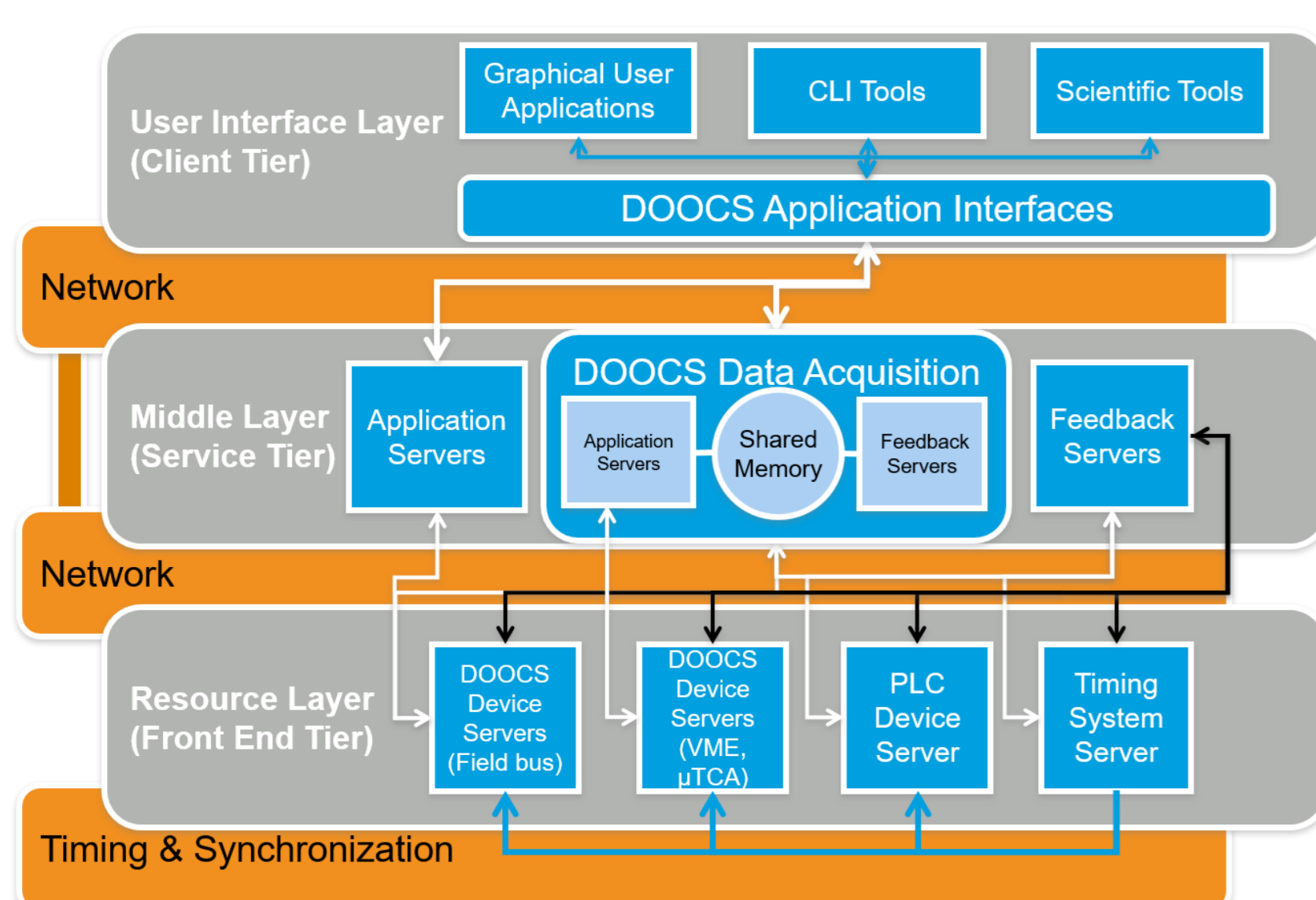
PETRA III

- 2300-metre-long storage ring feeding 24 user beamlines
- Operated either in brightness mode (480 equally distributed bunches, 120 mA stored beam) or in timing mode (40 equally distributed bunches, 100 mA stored beam)
- Research groups from all over the world use the particularly brilliant, intense X-ray light for a variety of experiments - from medical to materials research

PETRA IV

- High-resolution 3D X-ray microscope for chemical and physical processes
- Will extend the X-ray view to all length scales, from the atom to millimetres
- Offers outstanding possibilities and optimal experimental conditions for industry
- Will replace PETRA III, but keeping the existing experimental halls
- An additional experimental hall will provide space for additional 18 user beamlines
- New booster synchrotron DESY IV

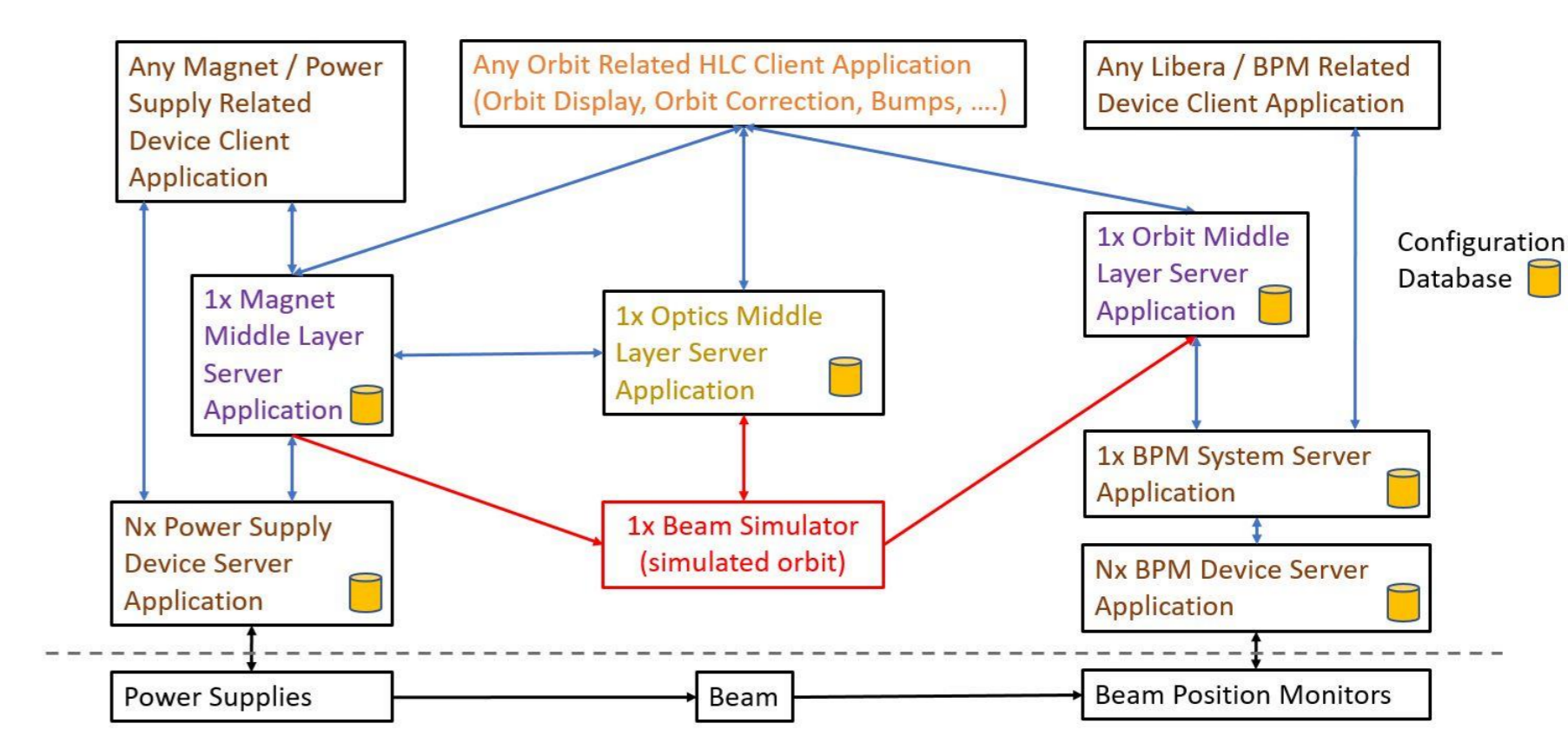
Control System Framework



Three-layer architecture of the Distributed Object-Oriented Control System (DOOCS)

- Distributed Object-Oriented Control System (DOOCS)
 - Architecture: Three-layer, distributed client-server
 - Transportation layer: Industrial RPC protocol, ZeroMQ (being implemented)
 - Implementation:
 - Server: C++
 - Client: C++, Java, Python, MATLAB
 - Device interface: Variety of fieldbus and hardware interfaces
 - Integrated data acquisition service (DOOCS DAQ)
 - Interoperability: Client API provides access to
 - EPICS (facility control system at DESY)
 - TANGO (beamline control system at PETRA)
 - Development and Simulation Environment (Virtual PETRA)

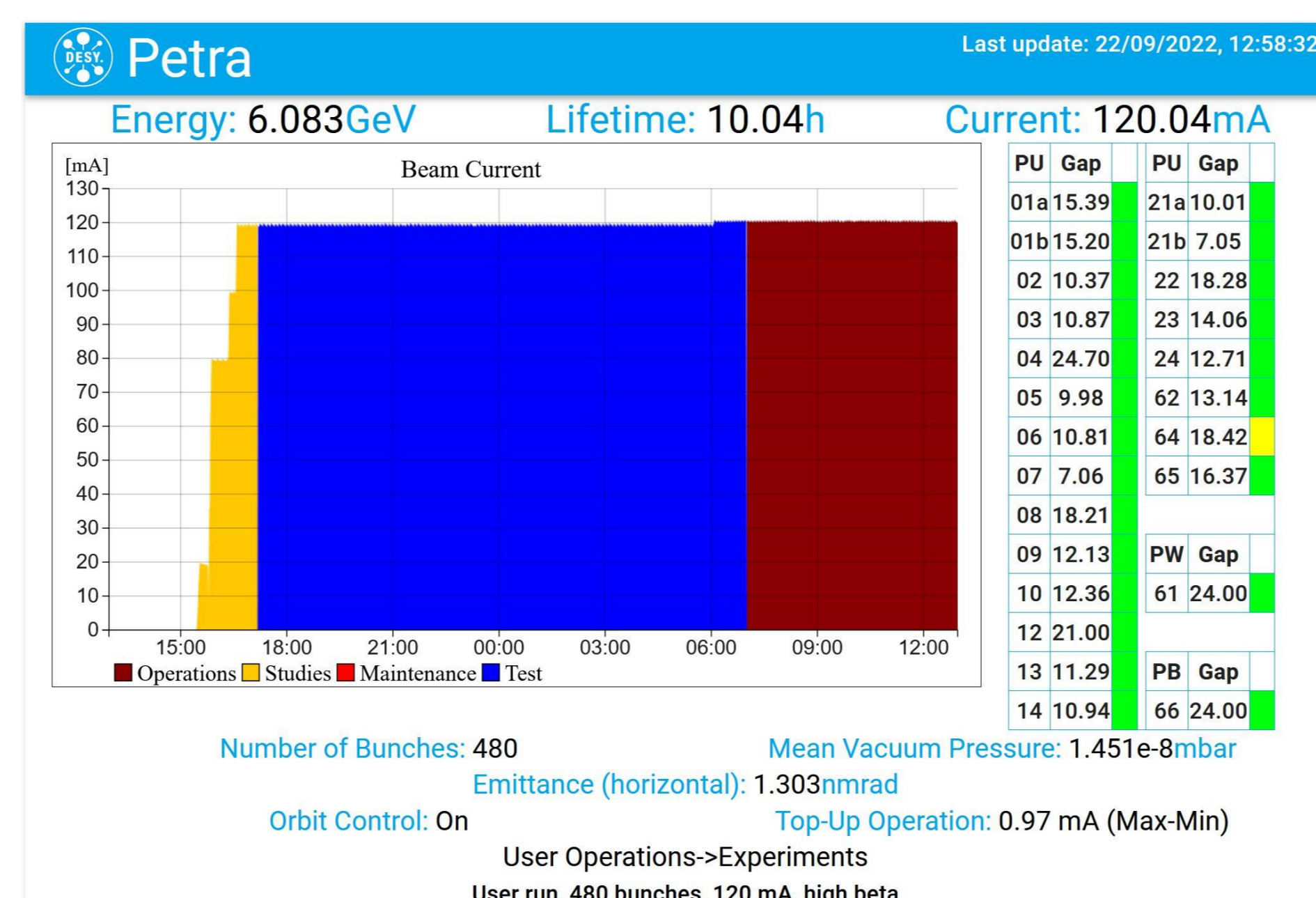
(Virtual)PETRAIV (Magnets / Power Supplies, HLC, Liberis / BPMs)



Real PETRA ↔ Virtual PETRA
(Example: Orbit control)

Graphical User Interfaces

- Java DOOCS Data Display (JDDD):
 - Tool of choice for the standard beam operation as well as operating technical accelerator devices and systems
 - Thin-client approach with a functional and rich set of widgets
- Python and MATLAB:
 - Tool of choice for rapid prototyping and visualization of scientific procedures and data
- Progressive Web Apps (PWA):
 - Tool of choice for dashboard-like applications
 - Based on React JavaScript framework



PETRAIII operational overview implemented as Progressive Web App using React framework

Device Interfaces

- Interfaces for triggered, high-performance applications:
 - Compliant with MicroTCA.4 technology
 - Linux
 - Remotely manageable
 - Specific modules, e.g. Timing, ADC, Digital I/O processing
- Interfaces for conventional slow-control applications:
 - Compliant with industrial process control standards
 - Generic bridge server available for, e.g.:
 - OPC UA servers
 - Beckhoff controller
 - PLC

Acquisition and Archiving of Operational Data

- Data:
 - Time series data:
 - Number of devices: ~ 10.000
 - Acquisition rate / duration of storage:
 - Typically: 10 Hz / unlimited, max. 100 Hz / limited
 - In rare cases: 10kHz (→ DOOCS DAQ)
 - Snapshot data: Event triggered
- Database:
 - Timescale (extension of PostgreSQL)
 - Mature, robust technology
 - Variety of data types (including arrays)
 - Good scaling behaviour
 - Can be operated as a distributed cluster
 - Large number of specific processing functions
 - Ongoing prototype development (performance exploration, data pipeline, data reduction strategies, local data buffering)

Management of Configuration Data

- Configuration data:
 - Include:
 - Hardware-related data: e.g. calibration constants
 - Software-related data: e.g. control system addresses
 - Not include:
 - State-dependent operational setpoint data (→ Save&Restore tool)
 - Different versions of software applications (→ GitLab)
- Change management:
 - Formalized change workflow
 - Through control system (but monitored against references)
- Database:
 - Relational
 - Ongoing prototype development (table structure, change history, unique identifier / temporal validity scheme)