



DEVPYLON, DEVVIMBA...GAME CHANGERS AT LULI



TUMBCMO32

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ABSTRACT

This poster focuses on two linked software components: DevPylon and DevVimba. Each affected to a type of cameras: Basler via PyPylon wrapper interface of Pylon Software suite and Prosilica via Vimba SDK library, respectively. These two **Tango** [1] devices are Python scripts constructed and generated via **POGO** [2]. They offer a specific way to monitor more than 100 CCD cameras in the facility at an image acquisition and display rate up to 10 Hz for a maximum of 300-shot at 1-minute rate per day and on an always-ON mode throughout the day.



PURPOSE

2 types of **cameras**, 2 **Tango devices** with similar properties and attributes: ONE GUI

TANGO-CONTROL ADVANTAGES

Multi-languages, OS independent and valuable panel of tools for management and monitoring

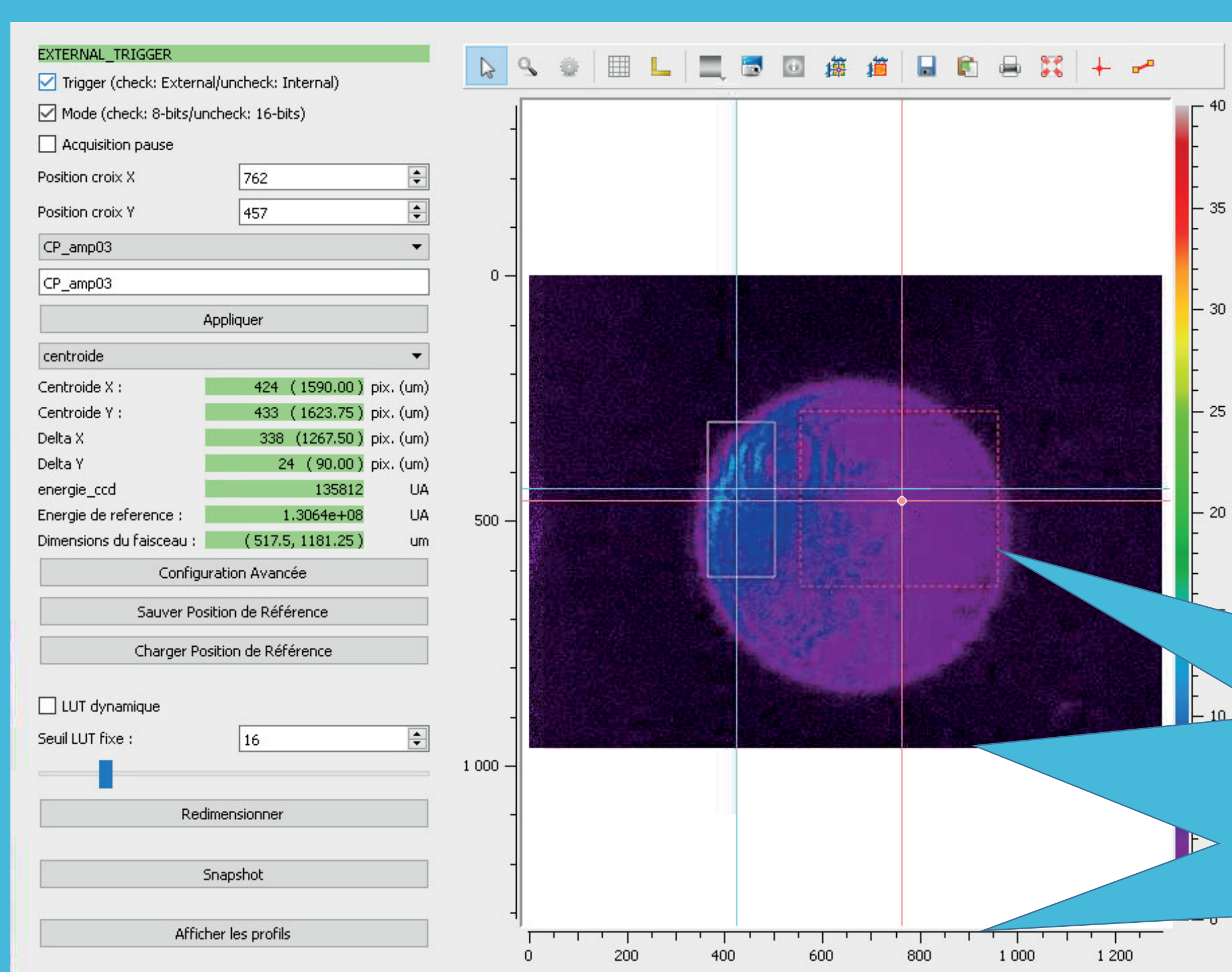
AVAILABILITY

Find these two Python devices on the Tango-Controls gitlab!



CAMERAS

ONE GUI AND ONE ONLY



BASLER

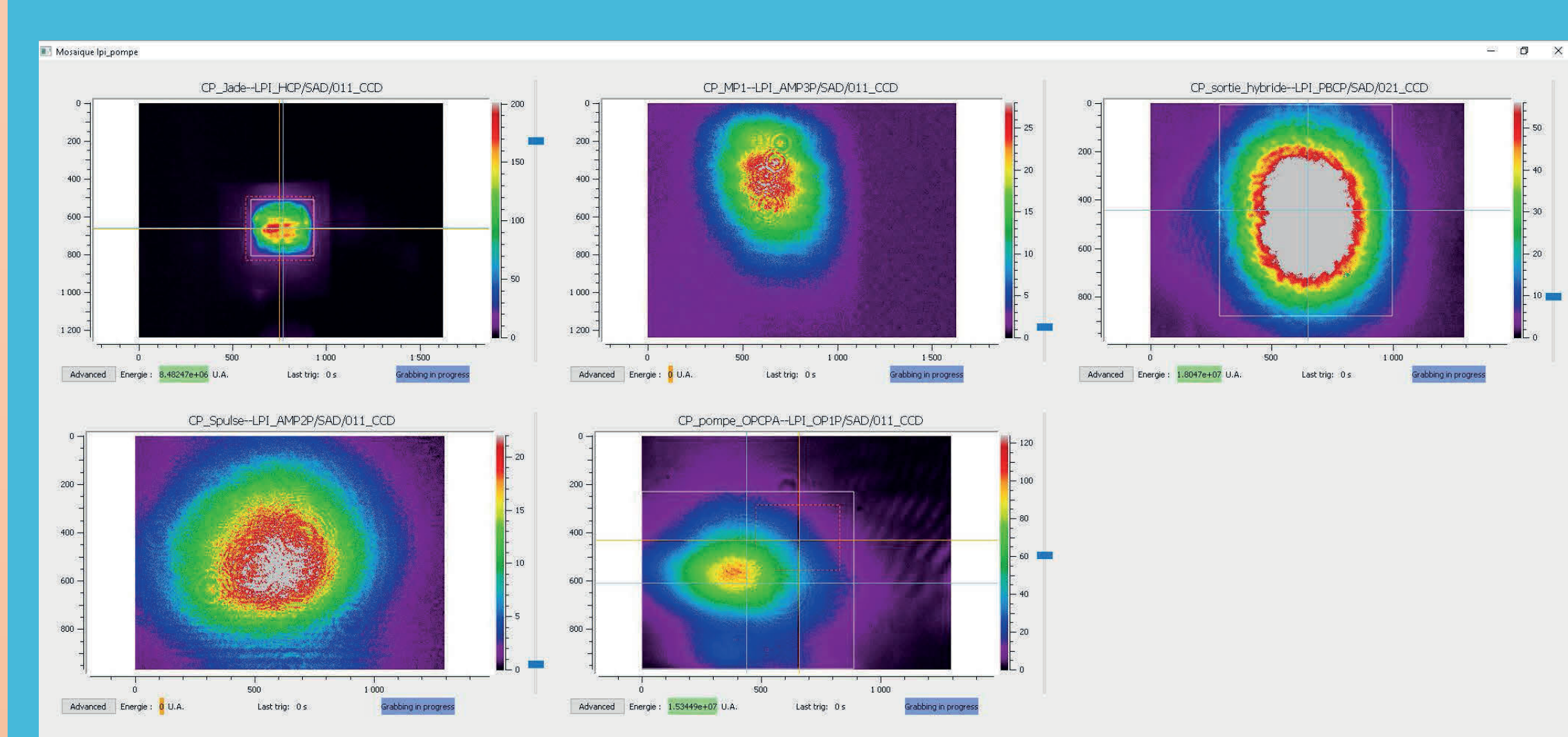
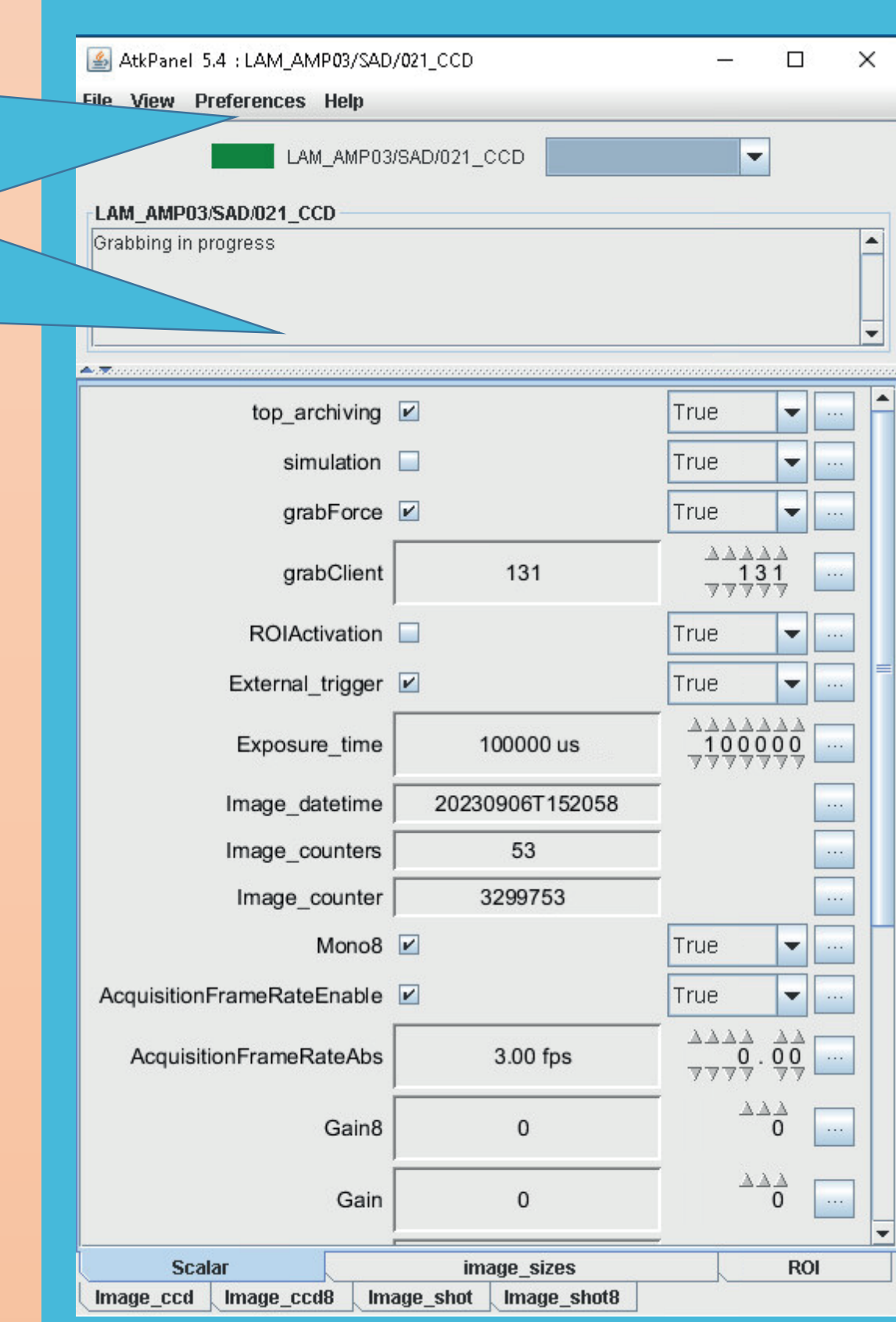


PROSILICA



A SINGLE EXPERIENCE FOR A HAPPY USER

SIMILAR ATKPANELS



The DevCalculs device associated with DevPylon and DevVimba allows a real-time computation of centroid, alarm zone, local maximum, etc. and also displays user-defined references.

The next step will be to integrate other cameras and create a library to consolidate these features; it's a big investment of resources for our lab at this moment due to the use of specific PyPylon/Vimba libraries. Interested? Come and join us! **Tango** is the Future. **Soon on The Moon!?**

ACKNOWLEDGMENT & REFERENCES

Special thanks to Tango community colleagues who shared experience and helped construct and develop Apollon Control System
[1] Tango Controls website: <http://www.tango-controls.org>
[2] POGO is a Tango Controls class generator

CONFERENCE LINK

See our other poster TUPDP012 about Apollon facility command-control in the session on Tango at LULI

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